

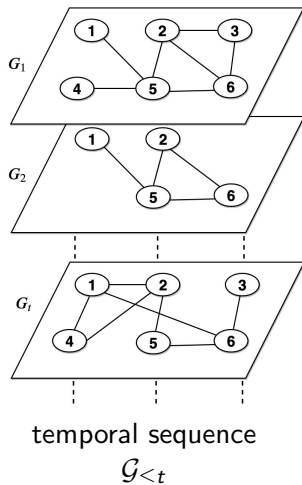
A Combinatorial Multi-Armed Bandit based method for Dynamic Consensus Community Detection in Temporal Networks

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Community Detection (CD) in Temporal Networks



- need for modeling the change events in the communities and tracking their evolution.
- **Challenges:** choice of timestep width, different type and occurring rates of community evolution events.
- incremental nature of the problem

Applications

- enhanced group-recommendation
- user behavior prediction
- evolution of user interaction patterns in relation to real-world events

Existing works on CD in Temporal Networks

Existing approaches:

- try to discover a sequence of mappings for the community structures independently derived at each time step
- detect a community structure for the current topology as dependent on the structure(s) from prior time step(s)
- update a community structure in order to reflect newly observed changes
- aggregate the various snapshots of the network in order to enable a static community detection method

Limitations of existing approaches

- require to match and/or track the evolution of communities over time
- depend on specific community-change events (merge, split, etc.)
- depend on restricted graph models
- assume the same nodes and number of communities for each snapshot

CD in Temporal Networks as Consensus problem

Requirement: balancing over time between the need for embedding long-term changes observed in the community formation and the need for capturing short-term effects and newly observed community structures.

- give more importance to the more recent community structures in the consensus generation

Dynamic consensus community structure

A community structure that encompasses the knowledge about newly observed as well as the previously detected communities in a temporal network

Dynamic consensus community detection problem (DCCD)

Input: Given the temporal graph sequence $\mathcal{G}_{\leq t}$ (undirected and unweighted graphs) and associated set of detected community structures (non-overlapping communities)

Output: for any time $1 \leq t \leq T$, compute a dynamic consensus community structure $\mathcal{C}_{\leq t}$ such as to maximize:

$$R(T) = \sum_{t=1}^T Q_t(\mathcal{C}_{\leq t})$$

where Q_t is a chosen quality criterion for a community structure, over the history (before t) of the network (e.g. multilayer modularity ¹).

¹A. Tagarelli et al. "Ensemble-based community detection in multilayer networks". Data Min. Knowl. Discov. (2017)

Dynamic Consensus representation model

Dynamic co-association matrix (DCM) \mathbf{M} : the (i, j) -th entry of \mathbf{M} , denoted as m_{ij} , stores the probability of co-association for entities $v_i, v_j \in V$, i.e., the probability that v_i and v_j are assigned to the same community, in the observed timespan

Computing meaningful co-associations and properly maintaining and updating the consensus community structure over time is challenging:

- avoid (re)computation of the consensus from scratch
- avoid to depend on any mechanism of tracking of the evolution of communities
- density of \mathbf{M}

Reinforcement Learning approach to DCCD problem

Reinforcement Learning:

- interrelated actions with unknown "rewards" ahead of time
- choose which actions to take in order to maximize the reward
- exploitation/exploration trade-off
 - exploitation: make the best decision given current information
 - exploration: gather more information

CD in temporal networks

- uncertainty about the temporal network system, and the structural changes and consequent decisions to take about the node memberships and structure of the communities
- balancing between relying on older community structures and newly observed ones

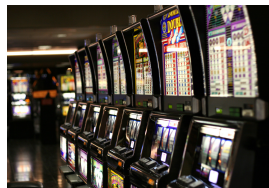
Multi-Armed Bandit (MAB)

- \mathcal{A} is a set of m slot-machines/arms to choose from
- each arm is associated with a set of random variables $\{X_i^t \mid 1 \leq i \leq m, t \geq 1\}$, $X_i^t \in [0, 1]$
- At each step t the agent selects/plays an arm $a_t \in \mathcal{A}$ and the reward $X_{a_t}^t$ is revealed
- The goal is to maximise the cumulative reward $R(T) = \sum_{t=1}^T X_{a_t}^t$
- The goal is pursued through an exploration/exploitation trade-off



Combinatorial Multi-Armed Bandit (CMAB)²

- At each step t the agent selects a **subset of base arms** (super arm) $A_t \subseteq \mathcal{A}$ and the rewards $X_{a_t}^t$ for all $a_t \in A_t$ are revealed
- the base arms belonging to A_t may probabilistically trigger other base arms not in A_t
- The reward of playing A_t , $R(A_t)$, is a linear/non-linear combination of the rewards of the selected and triggered base arms
- The goal is to maximise the cumulative reward $R(T) = \sum_{t=1}^T R(A_t)$



²Wei Chen et al. "Combinatorial multi-armed bandit and its extension to probabilistically triggered arms." The Journal of Machine Learning Research 17.1 (2016)

Translating the DCCD problem into CMAB (I)

- each pair $\langle v_i, v_j \rangle$ is a base arm and its semantics is assigning the nodes to the same community at a given time
- each pair $\langle v_i, v_j \rangle$ is associated with an unknown distribution (with unknown mean μ_{ij}) for the probabilities of co-association over time (they may change), whose mean estimate is the entry m_{ij} in DCM
- A superarm A_t is a set of base arms which corresponds to a dynamic consensus community structure i.e., a set of pairs $\langle v_i, v_j \rangle$ such that $c_i^{(t)} = c_j^{(t)}$

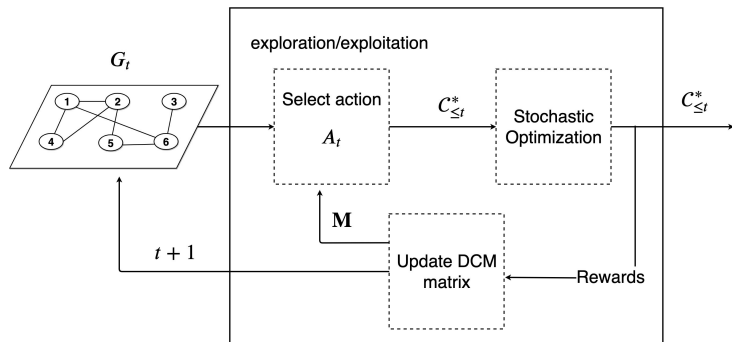
Translating the DCCD problem into CMAB (II)

- Playing a superarm A_t corresponds to:
 - 1 inducing a community structure from the played superarm
 - 2 performing stochastic relocation of nodes to neighbor communities (trigger base arms)
- the rewards associated to the entity pairs (base arms) are revealed after the relocation phase thus \mathbf{M} can be updated
- $R(A_t)$ corresponds to the quality of the solution after the relocation phase, e.g. modularity is a non-linear combination of rewards X_{ij}^t

$$R(A_t) = \frac{1}{d(\mathcal{V}_{[1..t]})} \sum_{i,j} \sum_{\ell=1}^t \beta^{t-\ell} \left(A_{ij}^\ell - \frac{k_i^\ell k_j^\ell}{d(\mathcal{V}_{[1..t]})} \right) \delta(X_{ij}^t)$$

$$X_{ij}^t = 0 \text{ if } c_i^{(t)} \neq c_j^{(t)}, 1/|c_i^{(t)}| \text{ otherwise}$$
$$\delta(X_{ij}^t) = 1 \text{ if } X_{ij}^t > 0, 0 \text{ otherwise}$$

Overview of the framework



- updates: $newEstimate \leftarrow oldEstimate + \alpha(newValue - oldEstimate)$
- exploration/exploitation: partition the DCM-graph/current snapshot

Algorithmic scheme

Algorithm 1 General scheme of CMAB algorithm for Dynamic Consensus Community Detection

Input: Temporal graph sequence $\mathcal{G}_{\leq T}$ ($T \geq 1$), bandit strategy \mathcal{B} , (static) community detection method \mathcal{A} .

Output: Dynamic consensus community structure $\mathcal{C}_{\leq T}^*$.

- 1: Initialize the dynamic consensus matrix \mathbf{M}
- 2: **for** $t = 1$ **to** T **do**
- 3: **if** \mathcal{B} decides for **EXPLORATION** **then**
- 4: Find a community structure $\mathcal{C}^{(t)}$ on G_t using \mathcal{A}
- 5: **else** {**EXPLOITATION**}
- 6: Partition the DCM-graph using \mathcal{A}
- 7: Infer a community structure $\mathcal{C}^{(t)}$ on G_t based on the DCM-graph partitioning
- 8: **end if**
- 9: Project the community memberships from $\mathcal{C}^{(t)}$ onto $\mathcal{G}_{\leq t}$
- 10: Stochastic optimization of $\mathcal{C}_{\leq t}^*$
- 11: Update the DCM matrix \mathbf{M} based on $\mathcal{C}_{\leq t}^*$
- 12: **end for**
- 13: **return** $\mathcal{C}_{\leq T}^*$

Instantiation of the algorithmic scheme (CreDENCE)

Algorithm 2 CMAB-based Dynamic Consensus Community Detection (CreDENCE)

Input: Temporal graph sequence $\mathcal{G}_{\leq T}$ ($T \geq 1$), (static) community detection method \mathcal{A} , bandit strategy \mathcal{B} , learning rate $\alpha \in (0, 1)$, relocation bias $\lambda \in [0, 1]$, temporal smoothness $\beta \in (0, 1)$, temporal window width $\omega \geq 1$.

Output: Dynamic consensus community structure $\mathcal{C}_{\leq T}^*$.

```
1:  $\mathbf{M} \leftarrow I_{|\mathcal{V}_1| \times |\mathcal{V}_1|}$ 
2: for  $t = 1$  to  $T$  do
3:   if  $\mathcal{B}$  decides for EXPLORATION then
4:      $\mathcal{C}^{(t)} \leftarrow \text{findCommunities}(G_t, \mathcal{A})$ 
5:   else {EXPLOITATION}
6:      $G_{\mathbf{M}} \leftarrow \text{buildDCMGraph}(\mathbf{M})$ 
7:      $\mathcal{C}_{\mathbf{M}} \leftarrow \text{partitionDCMGraph}(G_{\mathbf{M}}, \mathcal{A})$ 
8:      $\mathcal{C}^{(t)} \leftarrow \text{inferCommunities}(G_t, \mathcal{C}_{\mathbf{M}})$ 
9:   end if
10:   $\mathcal{C}_{\leq t}^* \leftarrow \text{project}(\mathcal{C}^{(t)}, \mathcal{G}_{\leq t})$ 
11:   $\mathcal{C}_{\leq t}^* \leftarrow \text{evalRelocations}(\mathcal{G}_{\leq t}, \mathcal{C}_{\leq t}^*, \lambda, \beta, \omega)$  {Modularity maximization}
12:   $\mathbf{M} \leftarrow \text{updateDCM}(\mathbf{M}, \mathcal{C}_{\leq t}^*, \alpha)$  {Exponential moving average}
13: end for
14: return  $\mathcal{C}_{\leq T}^*$ 
```

Evaluation

Data:

- 5 real-world datasets and synthetic networks³

Evaluation goals:

- Impact of learning rate α
- Efficiency evaluation
- Comparison with competing methods:
 - DynLouvain⁴
 - M-EMCD*⁵
 - EvoAutoLeaders⁶

Experimental setting: \mathcal{B} is epsilon-greedy and \mathcal{A} is Louvain algorithm.

³ G. Rossetti. *RDyn: graph benchmark handling community dynamics*. Journal of Complex Networks, 2017.

⁴ J. He and D. Chen. *A fast algorithm for community detection in temporal network*. Physica A: Stat. Mech. Appl., 429:87–94, 2015

⁵ D. Mandaglio, A. Amelio, and A. Tagarelli. *Consensus Community Detection in Multilayer Networks Using Parameter-Free Graph Pruning*. In Proc. PAKDD, pages 193–205, 2018.

⁶ W. Gao, W. Luo, and C. Bu. *Adapting the TopLeaders algorithm for dynamic social networks*. The Journal of Supercomputing, 2017.

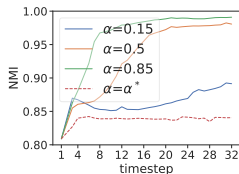
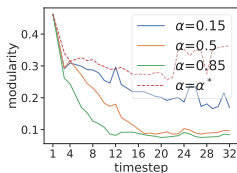
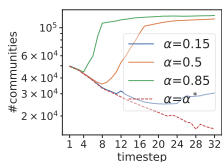
Datasets

Table: Main characteristics of our evaluation data. Mean \pm standard deviation values refer to all snapshots in a network.

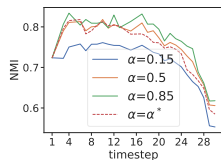
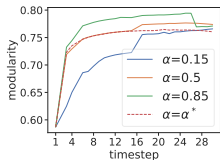
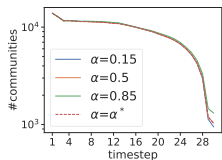
	#entities ($ \mathcal{V} $)	#edges	#time steps	node set coverage	edge semantics	% static (nodes, edges)	% hapax (nodes, edges)	% dynamic (nodes, edges)
<i>Epinions</i>	131 828	727 344	32	0.05	trust/distrust	(0.1, 0)	(80.8, 95.6)	(19, 2.2)
<i>Facebook</i>	63 731	17 676 817	30	0.87	friendship birth	(82.9, 2.7)	(0.2, 0)	(16.9, 1.9)
<i>Wiki-Conflict</i>	118 100	2 272 276	82	0.05	wikipedia editing	(0, 0)	(60.1, 83.4)	(38.9, 5.8)
<i>Wiki-Election</i>	7 118	102 906	44	0.08	vote assignment	(0, 0)	(49.7, 95.7)	(50.3, 2.2)
<i>You Tube</i>	3 223 589	41 955 741	8	0.62	friendship birth	(33.4, 6.7)	(12.4, 4)	(54.2, 11.6)

	network evolution rate			
	$e_t^+ = \frac{ E_t \setminus E_{t-1} }{ E_t }$	$e_t^- = \frac{ E_{t-1} \setminus E_t }{ E_{t-1} }$	$v_t^+ = \frac{ V_t \setminus V_{t-1} }{ V_t }$	$v_t^- = \frac{ V_{t-1} \setminus V_t }{ V_{t-1} }$
<i>Epinions</i>	0.97 \pm 0.007	0.98 \pm 0.008	0.65 \pm 0.08	0.69 \pm 0.06
<i>Facebook</i>	0.02 \pm 0.01	0	0.006 \pm 0.006	0
<i>Wiki-Conflict</i>	0.95 \pm 0.02	0.95 \pm 0.02	0.52 \pm 0.1	0.51 \pm 0.12
<i>Wiki-Election</i>	0.99 \pm 0.004	0.99 \pm 0.005	0.5 \pm 0.07	0.49 \pm 0.08
<i>You Tube</i>	0.16 \pm 0.06	0	0.14 \pm 0.06	0

Impact of learning rate (α)



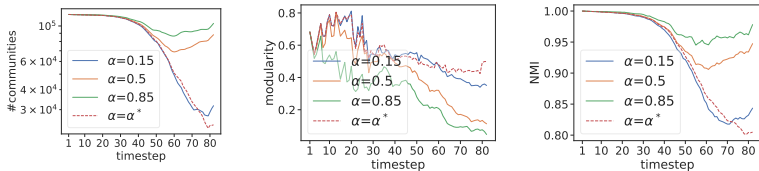
(a) Epinions



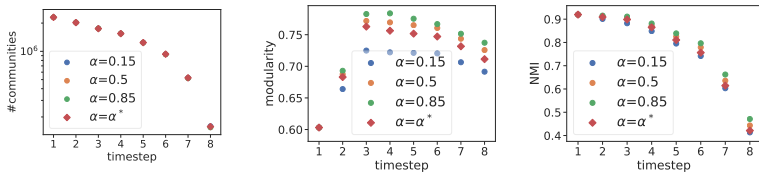
(b) Facebook

Figure: Size of the dynamic consensus by CreDENCE (left), multilayer modularity of the CreDENCE solutions (mid), and NMI between the CreDENCE consensus community structure and the snapshot's community structure, at each t (right).

Impact of learning rate (II)



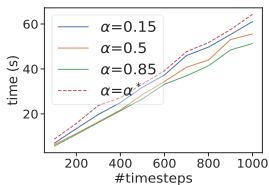
(c) Wiki-Conflict



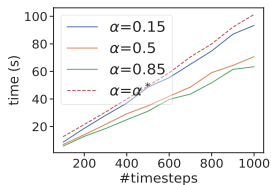
(d) YouTube

Figure: Size of the dynamic consensus by CreDENCE (left), multilayer modularity of the CreDENCE solutions (mid), and NMI between the CreDENCE consensus community structure and the snapshot's community structure, at each t (right).

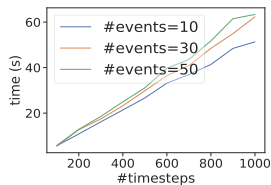
Efficiency evaluation



(a) 10 events



(b) 50 events



(c) $\alpha = 0.85$

Figure: Time performance on RDyn⁷ synthetic networks.

⁷G. Rossetti. *RDyn: graph benchmark handling community dynamics*. Journal of Complex Networks, 2017.

CreDENCE vs competing methods

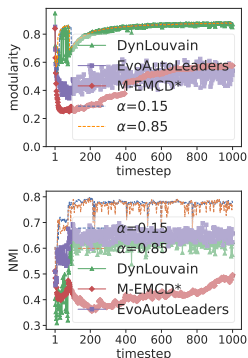


Table: Increment percentages of CreDENCE w.r.t. DynLouvain⁸ and M-EMCD⁹. Values correspond to the increment percentages averaged over all snapshots in a network, using the average best-performing α .

	DynLouvain		M-EMCD*	
	Modularity	NMI	Modularity	NMI
<i>Epinions</i>	1789.0%	-2.2%	13.9%	37.6%
<i>Facebook</i>	3.5%	9.4%	60.0%	37.5%
<i>Wiki-Conflict</i>	> 1.0 E+05%	-1.8%	-6.8%	37.6%
<i>Wiki-Election</i>	660.5%	-2.1%	32.0%	58.5%
<i>YouTube</i>	-0.1%	8.4%	21.1%	11.6%
<i>RDyn</i>	2.0%	24.97%	103.22%	81.1%

Fig. 4: Competitors vs. CreDENCE on RDyn: modularity (top), NMI (bottom).

Conclusion & Future Works

Summary:

- CMAB paradigm for CD in temporal networks
- novel problem of dynamic consensus community detection
- development of a fully defined algorithm for the DCCD problem
- deal with temporal networks that can have different structure and evolution rate

Future Works:

- evaluate the impact of different bandit strategies (e.g., UCB, Thompson sampling)
- learning the model parameters to best fit the community structure and evolution in a given temporal network

Thank you for your attention.
Questions?